Kinematic characteristics and laterality quotient predict interlimb transfer of sensorimotor adaptation

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Methods

Humans can adapt their reaching behavior to various perturbations such as prismatic deviations, visuomotor rotations or velocity force fields. However, it is unclear whether/why adaptation generalizes to the non-exposed limb.

1- Paradigmatic Investigation: Here we hypothesize that generalization may depend on the visual **context.** Indeed, interlimb transfer has been observed without vision of the limb or even with an indirect visual feedback of the limb (e.g., a cursor) [1, 2] while no transfer has been found with vision [3, 4]. The underlying processes may rely on credit assignment issues, i.e. the source of errors [5] and/or cognitive

Two groups of young, right handed adults and a group of 2 deafferented subjects had to reach toward flashed targets on a rotating platform:

Vision- Proprioception group (VP group) N=10, 5 males 5 females; mean age : 23.3 years

Vision group (V group) N=2, 1male (IW) 61 years old 1 female (GL) 65 years old

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Hypothesized relationship between credit assignment and generalization [5]

2- Idiosyncratic Investigation: A classification model was developed to investigate whether individual kinematics and subjects' characteristics could be linked to interlimb transfer.

3- Hypothesis Confirmations: We tested 2 proprioceptively-deafferented subjects and hypothesized that they would not be able to transfer since 1) proprioception has been shown to be important for updating the internal model of limb dynamics, 2) subjects rely on vision which we hypothesized may prevent interlimb transfer. Also, it allowed us to further test the generalization capacities of the model.



with a receiver operating characteristic (ROC) curve. It displays the probabilities in term of sensitivity and specificity of the model at each decision threshold (from 1 to 0).

Results

	1- Adaptation (Dominant Arm)	3- Awareness and credit assignment of errors	5- Test and comparison with deafferented subjects	
A	Per-rotation A A A A A A A A A A A A A	Awareness of errors in PER- Assignment of PER-errors to internal factors	GL's DA trajectories IW's DA trajectories PER- POST A 45 45 15 15	

internal factors.



Reaching direction at 150 ms of the DA in each experimental phase

A) Evolution of the initial direction of reaching movements in both groups in Pre-, Per- and Post-rotation phase.

B) Top view trajectories of one subject of the VP group.

C) Mean initial direction (at 150 ms) differed in Pre-, Per-initial and Postinitial (p<.000).



4- Classification Model of Transfer (NDA)







Trials

2- Interlimb Transfer (Non Dominant Arm)



Reaching direction of the NDA in Pre- and Post-rotation phases A) Top view trajectories of the NDA for one subject of the VP group **B)** Mean initial direction (at 150 ms) of the NDA differed between preand post-rotation phase (p<.05). There was no significant effect of group and no significant interaction.

(test dataset) on the basis of the 20 means control subjects (training dataset). **D)** NDA trajectories. The 2nd figure represents the comparison of the 99% confidence interval of the baseline with the first trial of the Post in term of AD.

each

both

probability to be in the class « transfer »



Discussion

On average in each group, we observed interlimb transfer to the untrained NDA. The questionnaire analysis showed that conscious awareness, or attribution of trajectory errors to internal causes, did not seem to influence interlimb transfer. Thus, we found no evidence that visual or proprioceptive feedback, or conscious mechanisms determine interlimb transfer.

We noticed a substantial inter-subject variability in transfer and developed a model which correctly predicted the presence or not of interlimb transfer with an accuracy of 95% based on 3 variables: variability of initial movement direction and peak velocity of the DA during the adaptation phase, and laterality quotient. Greater variability [7], peak velocity and laterality quotient predicted interlimb transfer of force-field adaptation.

Thus, in our experiment, parameters based on the subjets and their kinematics explained better interlimb transfer than paradigmatic conditions.

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